

# The International Geomagnetic Reference Field (IGRF) and its use in prediction

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# Talk Outline

1. The International Geomagnetic Reference Field
2. Data Sources
3. Results from IGRF-11: Internal Field 2010-2015
4. Prediction Problems
5. Outlook

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- ▶ Includes a description of both the present field and an estimate of the linear secular variation (rate of change) **for the upcoming 5 years.**
- ▶ **Goal:** To provide a reliable, stable, reference field agreed upon by geomagnetic modellers for the use of wider community.

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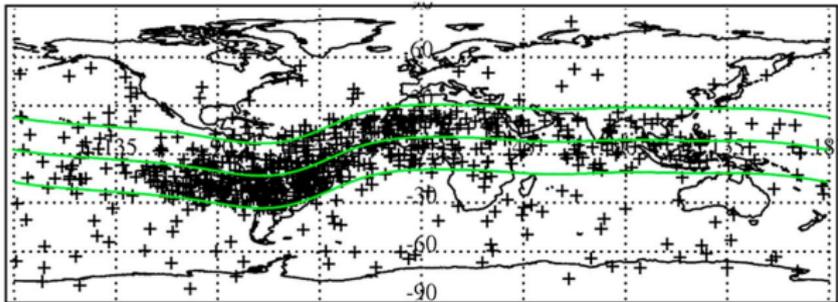
- ▶ Geophysical Exploration
- ▶ Directional Drilling
- ▶ Aviation
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### ▶ Private individuals

- ▶ esp. navigation/directional
- ▶ ~ 2 million queries per year at NGDC online declination calculators.

## Example: study of GPS scintillation

### COSMIC March 2007, 90<sup>th</sup> Percentile S4



**Fig 1.1:** Map of maximum S4 scintillation index from March 2007, 18-06 LT, 150-500km (F region), altitude from the COSMIC satellite constellation; 1 Hz, L band GPS (radio wave) data. From Dymond et al. (2012).

- ▶ Field geometry (e.g. IGRF) affects the frequency of observation of scintillations, indicative of plasma bubbles in the ionosphere.

## 1.3 Form of the IGRF model

- ▶ IGRF represents the geomagnetic field  $\mathbf{B}$  produced by internal sources in a source free region where  $\mathbf{B} = -\nabla V$  and

$$V(r, \theta, \phi, t) = a \sum_{n=1}^N \sum_{m=0}^n \left(\frac{a}{r}\right)^{n+1} [g_n^m(t) \cos m\phi + h_n^m(t) \sin m\phi] P_n^m(\cos \theta). \quad (1)$$

- ▶ Gauss coefficients  $g_n^m$  and  $h_n^m$  are provided for the main field at epochs separated by 5 year intervals between 1900.0 and 2010.0.
- ▶ Predicted (linear) time-dependence in upcoming five years:

$$g_n^m(t) = g_n^m(T_0) + \dot{g}_n^m(T_0)(t - T_0), \quad (2)$$

for a reference epoch  $T_0$  and  $\dot{g}_n^m$  the linear rate of change of  $g_n^m$ .

- ▶  $g_n^m$  and  $\dot{g}_n^m$  are determined by fitting to geomagnetic observations.

## 1.4 Latest IGRF update in 2010

- ▶ 8 institutions submitted candidate models for latest IGRF-11 revision:
  - NGDC/NOAA USA (Led by S. Maus)
  - IPGP, France (Led by E. Thébault)
  - DTU Space, Denmark (Led by N. Olsen)
  - GFZ, Germany, (Led by V. Lesur)
  - IZMIRAN, Russia, (Led by T. Bondar)
  - EOST, France, (Led by A. Chambodut)
  - BGS, U.K., (Led by B. Hamilton)
  - NASA, GSFC, USA, (Led by W. Kuang)
  
- ▶ Candidate models were assessed by task force and weighted to obtain final model (see Finlay et al., 2010 in EPS special issue).

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## 2.1 Data sources: Observatories

- ▶ High quality, long-term observations from worldwide network.



**Fig 2.1:** Magnetic observatories in San Juan, Puerto Rico (left) and Godhavn, Greenland (right).

## 2.2 Observatory coverage

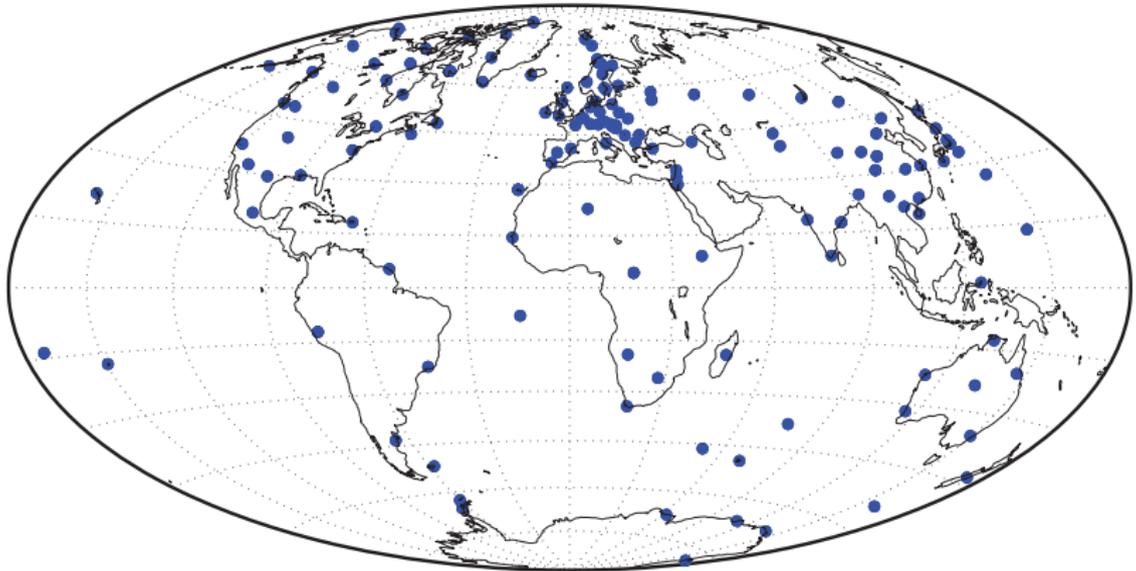


Fig 2.2: Locations of observatories used in determination of recent internal field models.

## 2.3 Data sources: Satellites

- ▶ Low Earth Orbit Satellites: short term but excellent global coverage.

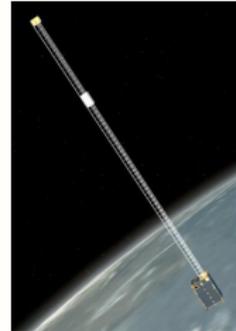
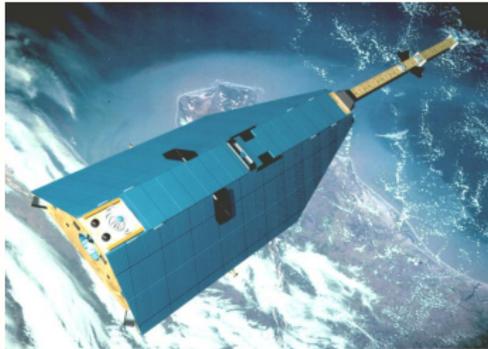
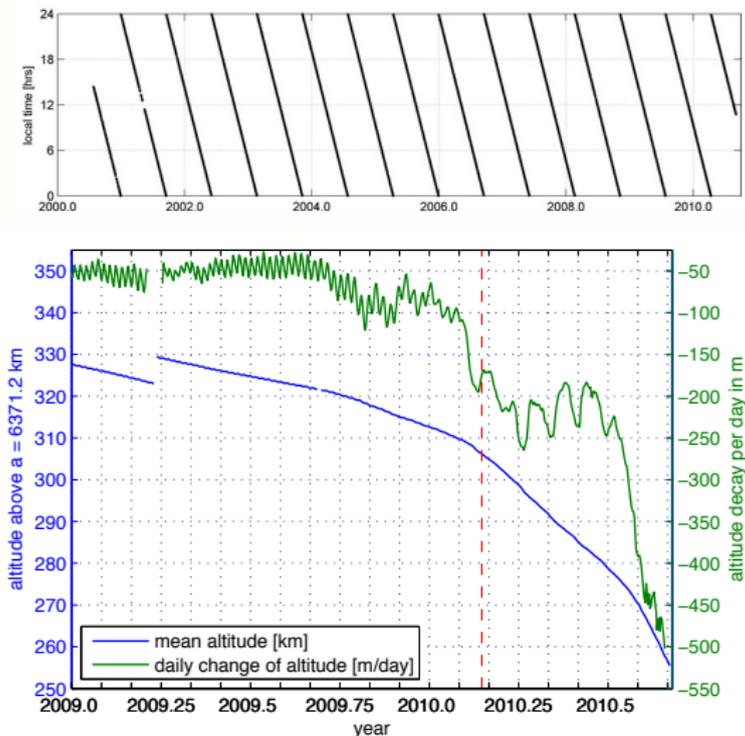


Fig 2.3: Satellites CHAMP (left) and Ørsted (right).

## 2.4 Data sources: CHAMP Orbit



Local time evolution of the ascending node of the CHAMP orbit (top) and decay of CHAMP orbital altitude (bottom). Courtesy of Nils Olsen.

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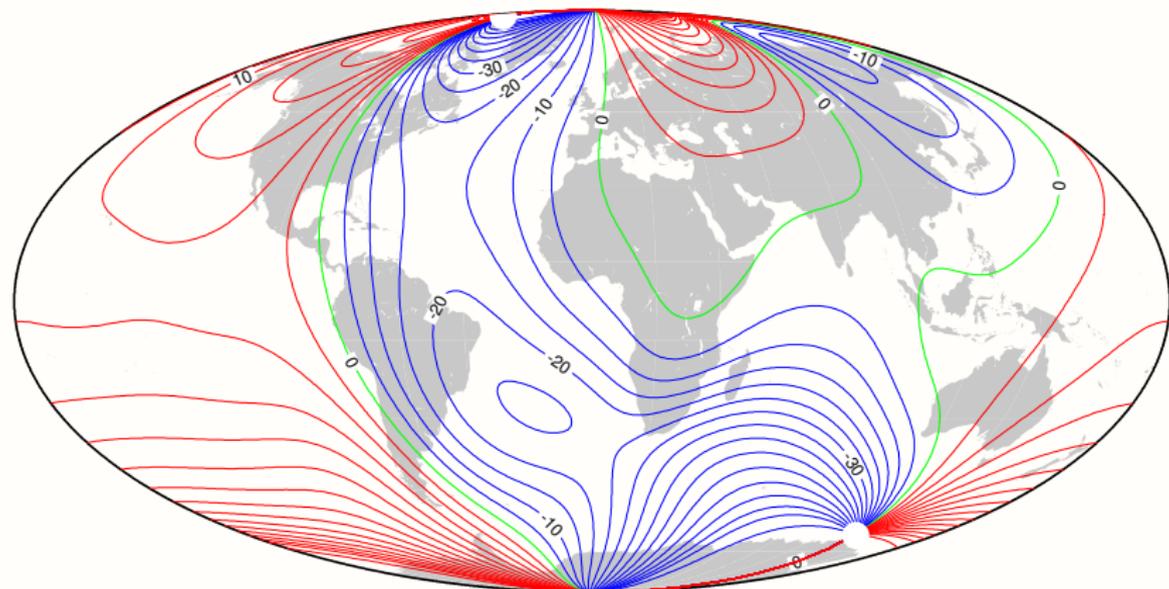


Fig 3.1: Declination  $D$  at Earth's surface in 2010.0 : units degrees.

## 3.2 IGRF-11 Inclination for Epoch 2010

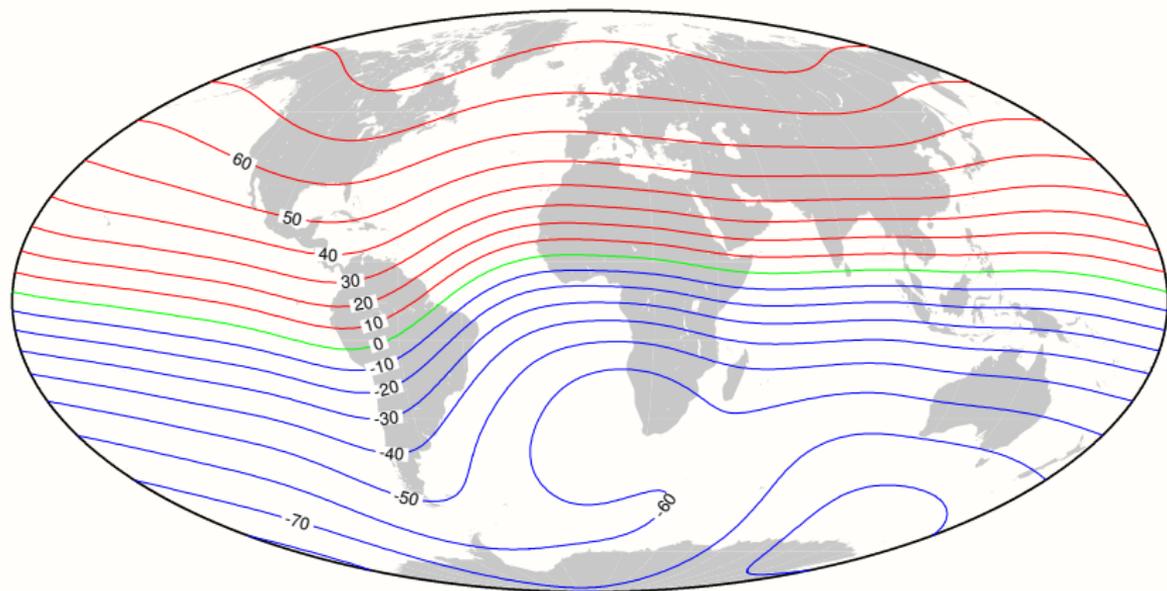


Fig 3.2: Inclination  $I$  at Earth's surface in 2010.0 : units degrees.

## 3.3 IGRF-11 Intensity for Epoch 2010

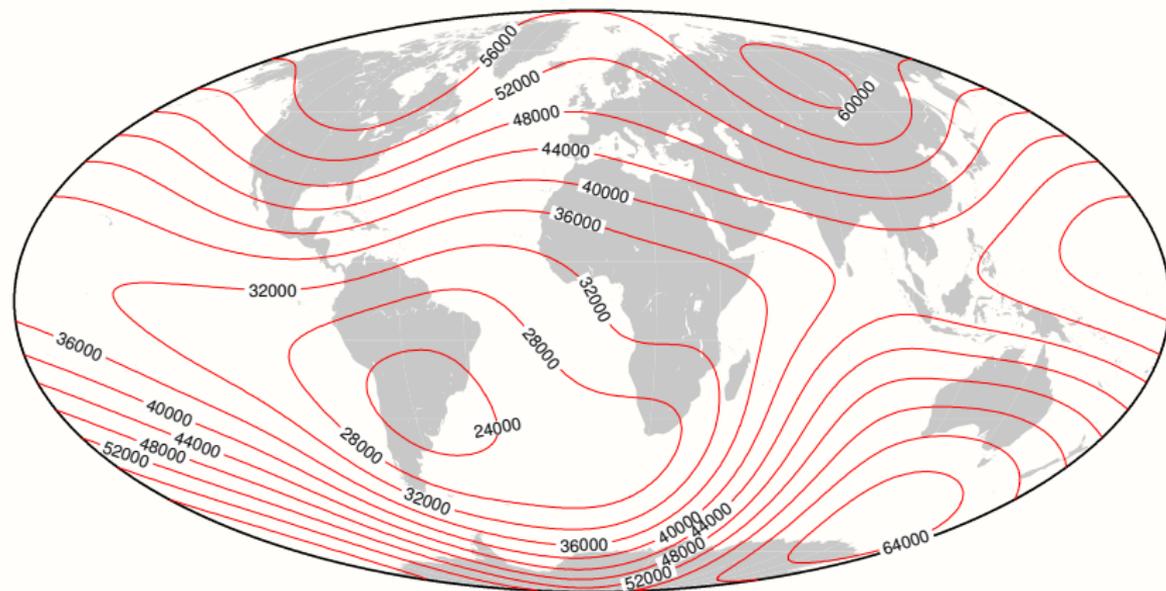
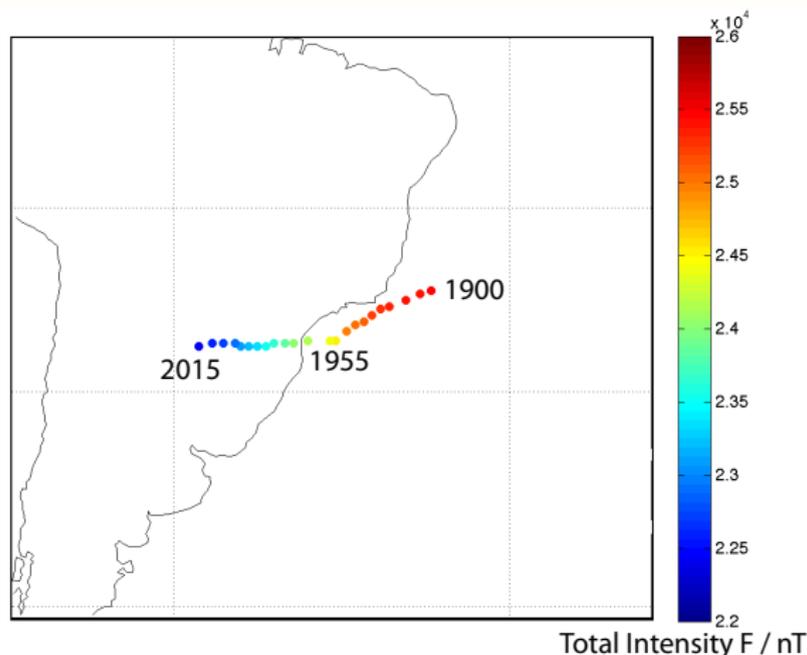


Fig 3.3: Field intensity  $F$  at Earth's surface in 2010.0 : units nanoTesla.

## 3.4 Evolution of South Atlantic Anomaly



**Fig 3.4:** Location of the point of lowest field magnitude with time; the colour scale indicates the magnitude of  $F$ , with blue representing smallest  $F$ , units are nT.

- ▶ South Atlantic anomaly is continuing to deepen and move westward (Talk of V. Lesur).

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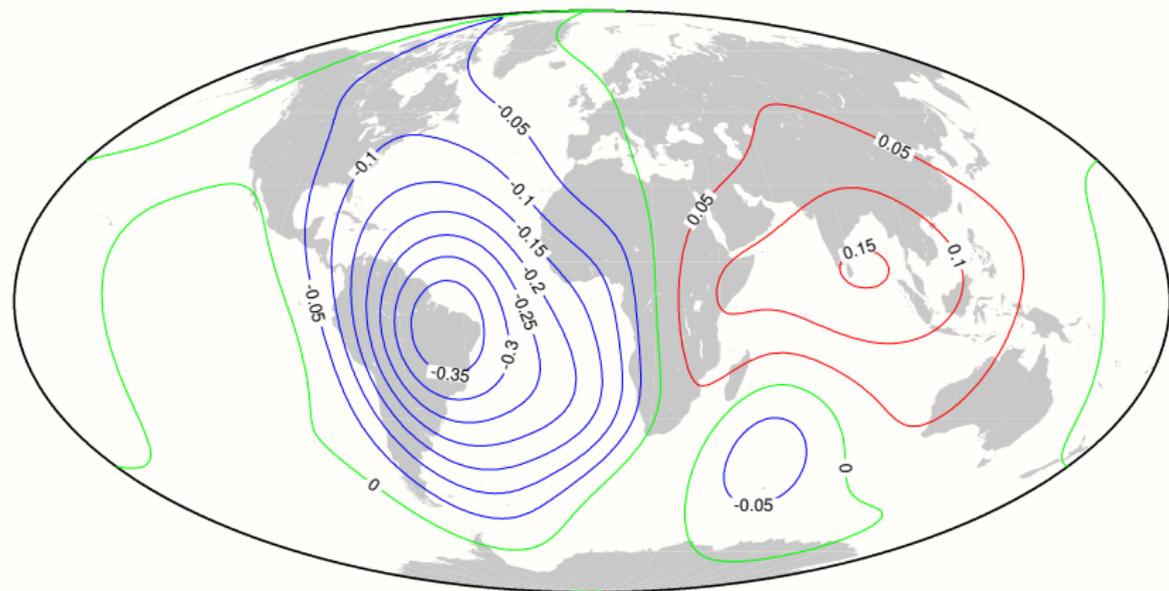
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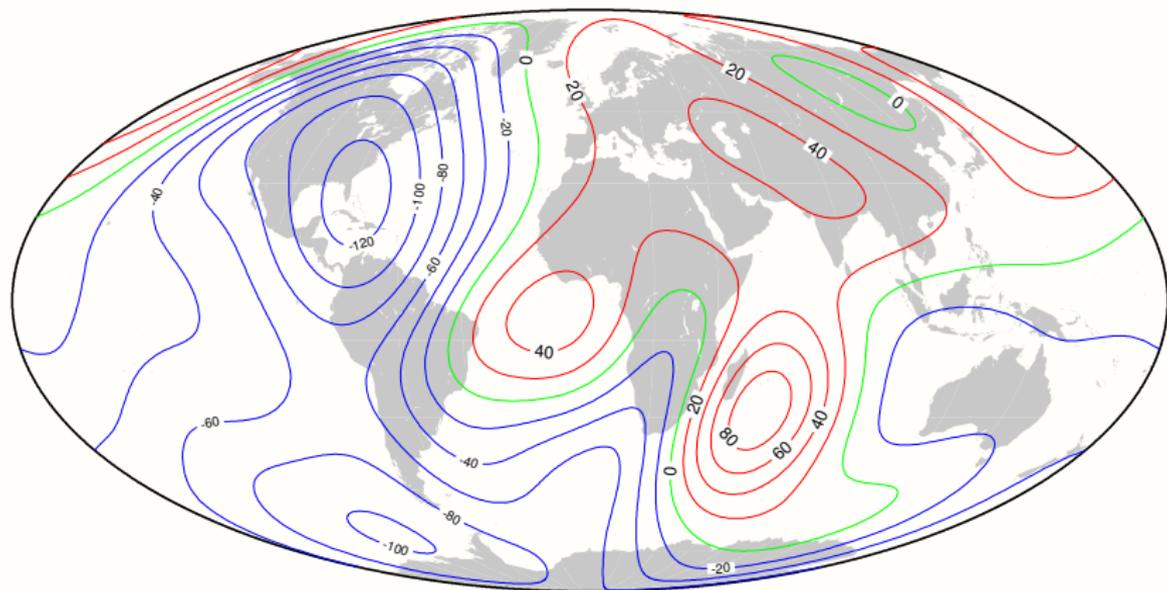
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- ▶ Changes per year are rather small (typically less than 0.2 % per year in F).
- ▶ But methods of prediction are known to be poor and lead to a cumulative error after 5 years of  $\sim 100\text{nT}$ .
- ▶ Mostly based on linear or quadratic extrapolation of change inferred at time of analysis or from the preceding few years.

## 4.2 IGRF-11 Inclination Change 2010-2015



**Fig 5.1:** Predicted annual change in  $I$  at Earth's surface between 2010.0 and 2015.0 : units degrees/yr.

## 4.3 IGRF-11 Intensity Change 2010-2015



**Fig 5.2:** Predicted annual change in  $F$  at Earth's surface between 2010.0 and 2015.0 : units nT/yr.

# Comparison of IGRF SV predictions with Obs. data

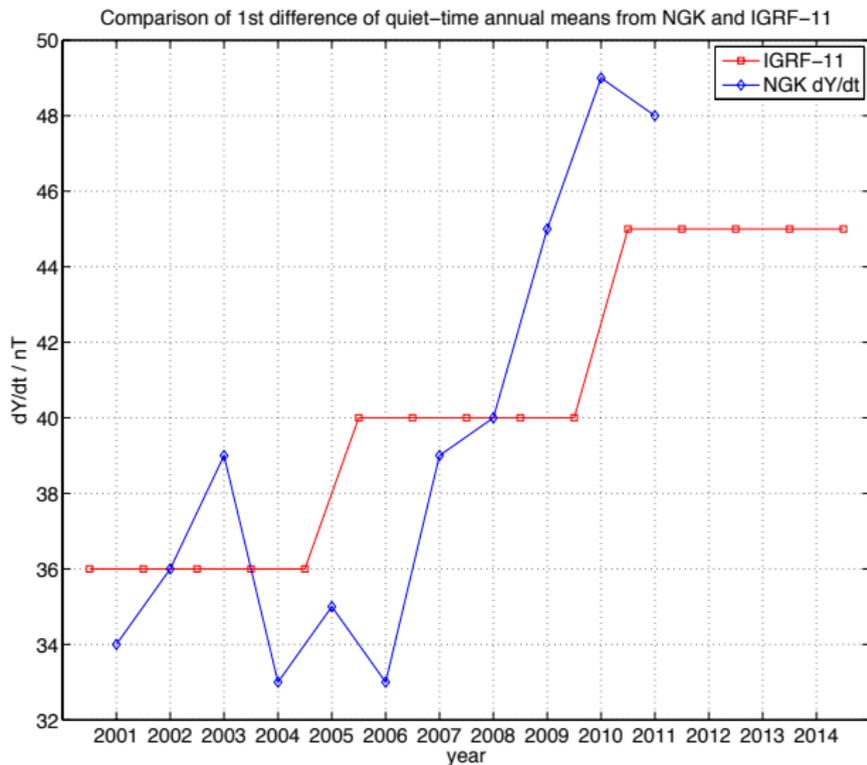


Fig 5.3: Comparison of IGRF-11 SV predictions with 1st differences of quiet time annual means.

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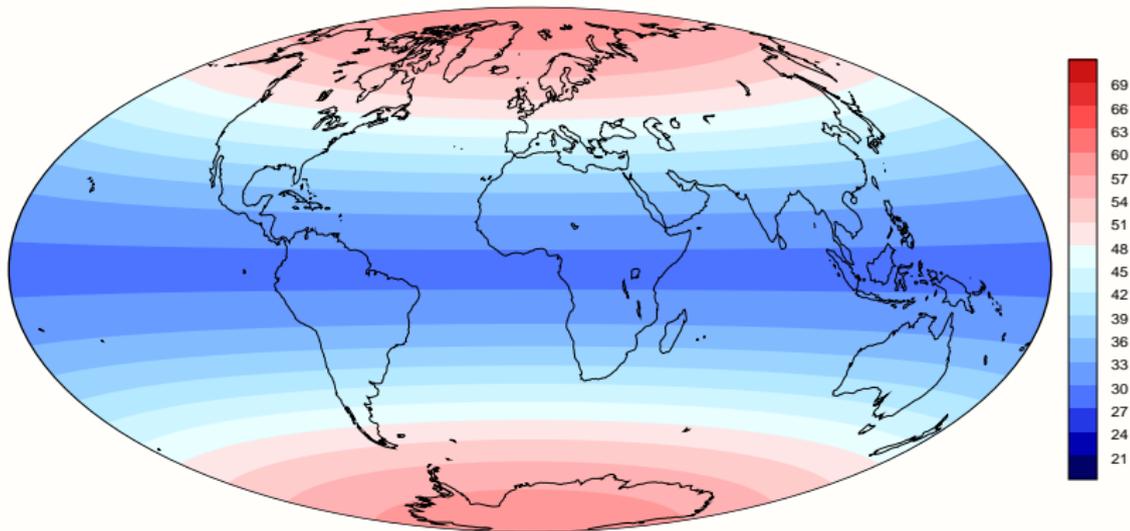
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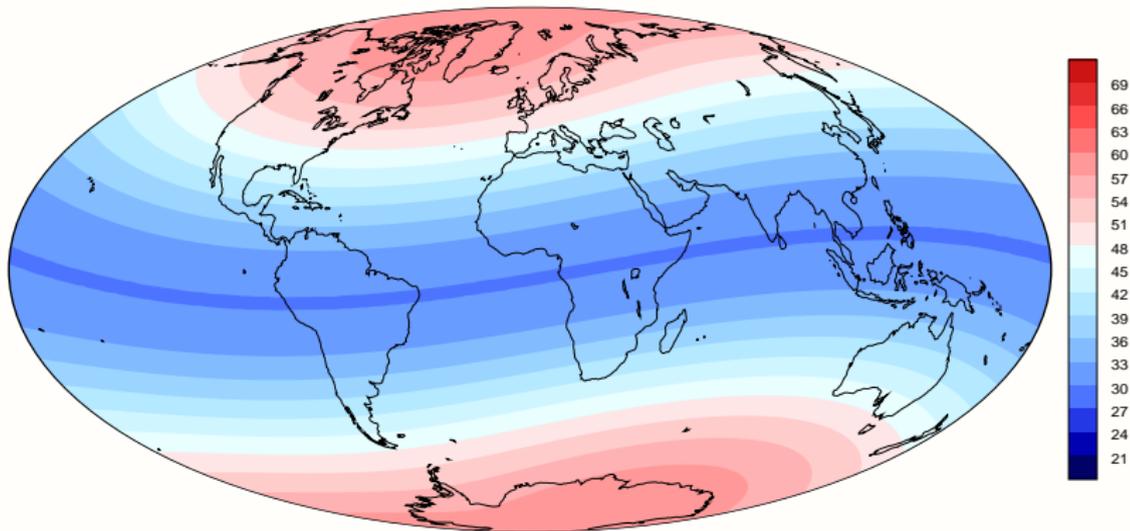
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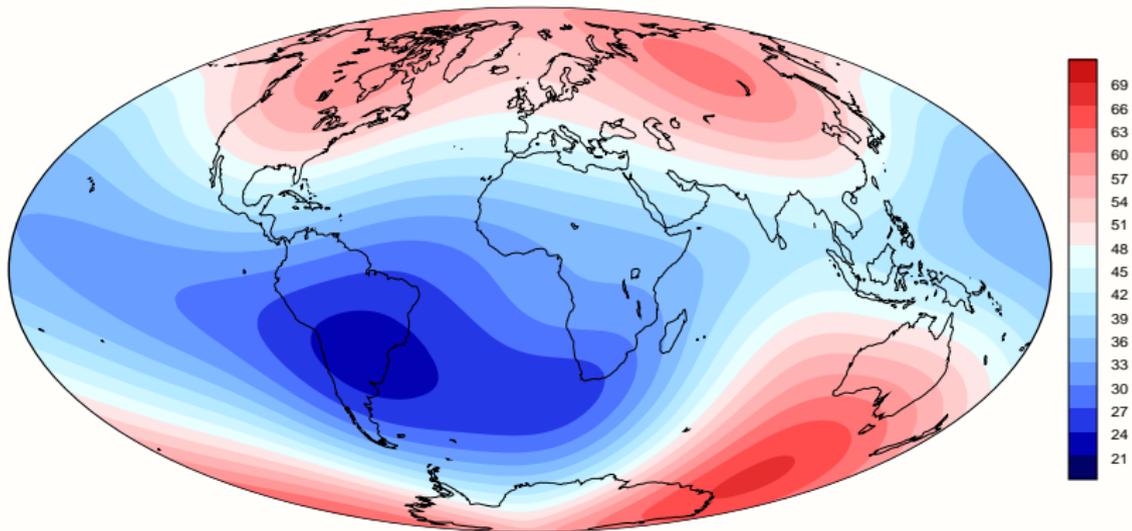
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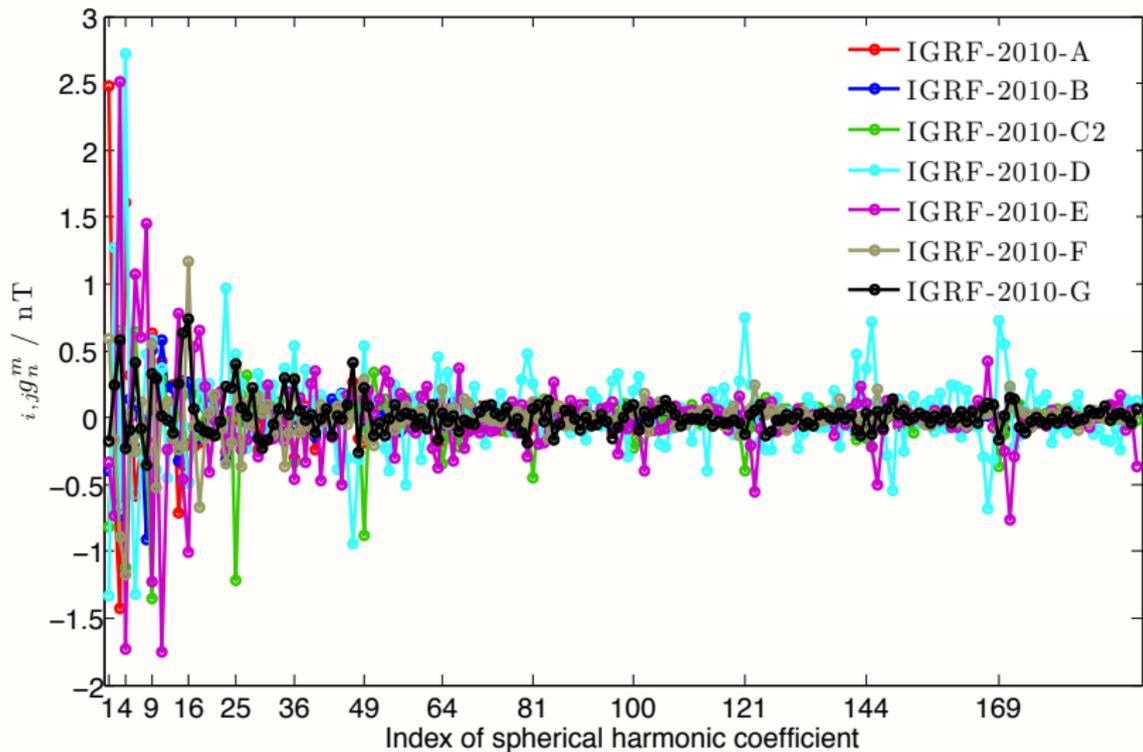
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- ▶ More appropriate prognostic physics and better accounting for observational uncertainties via data assimilation should help.
- ▶ IGRF can be a useful framework for testing new prediction techniques and driving improvements.

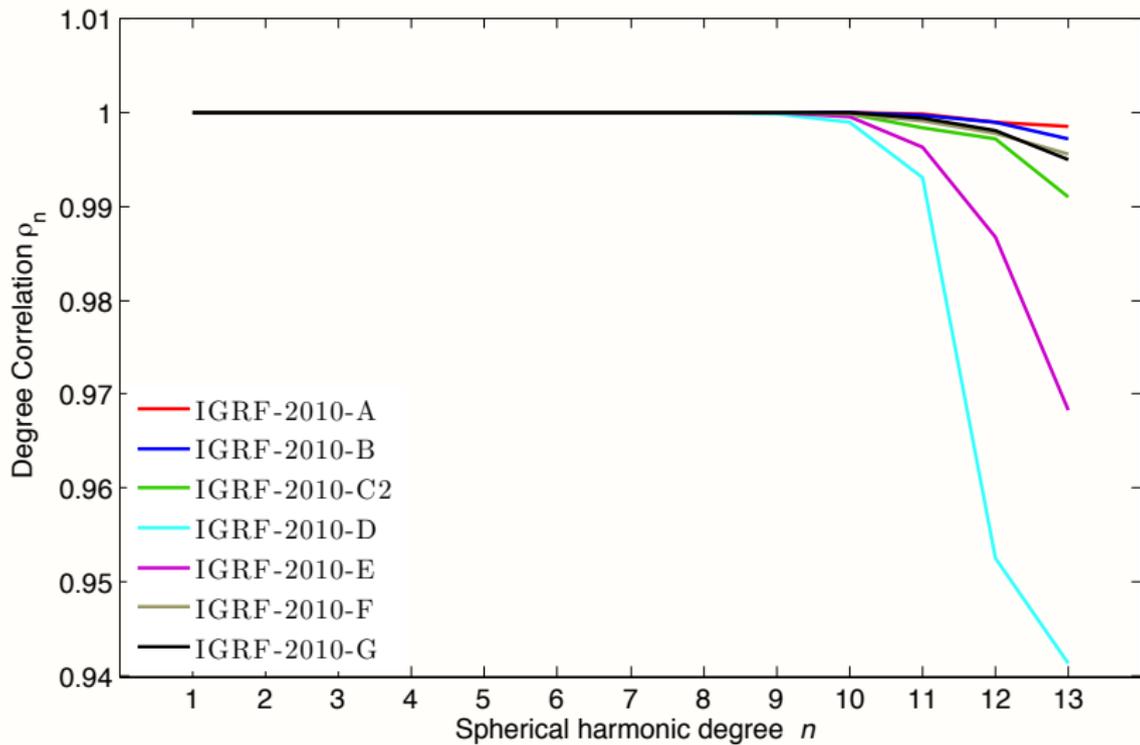


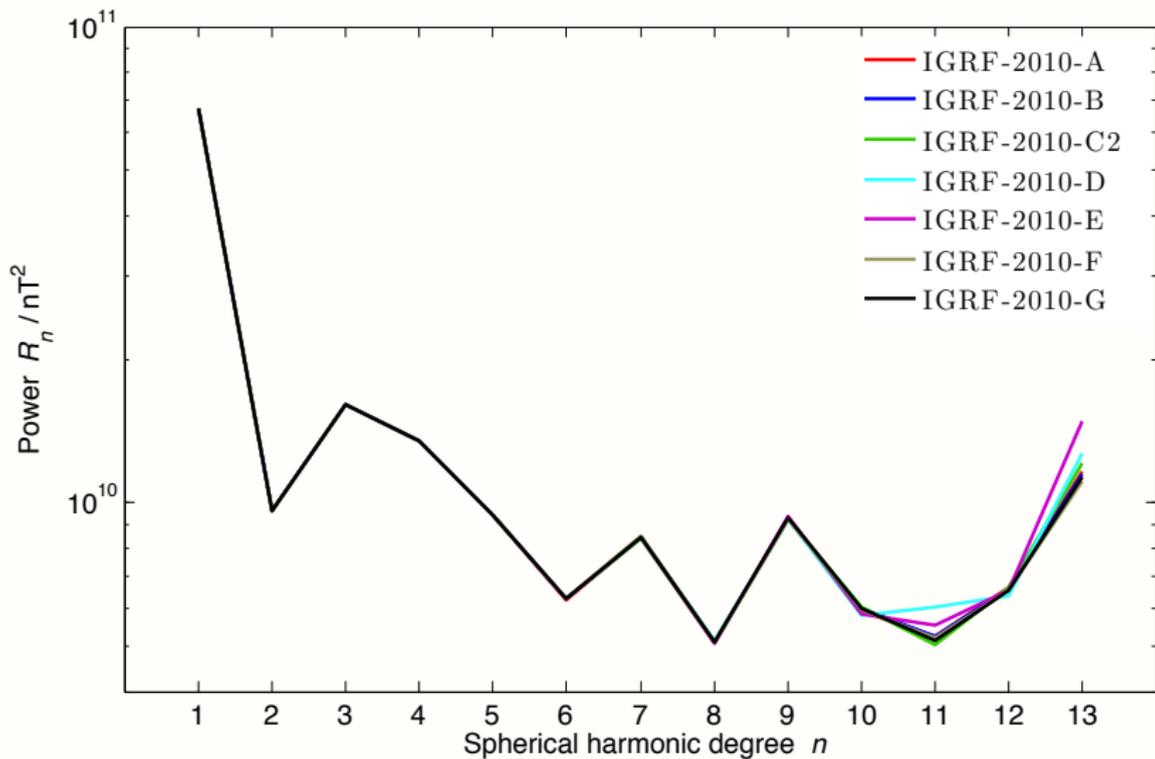


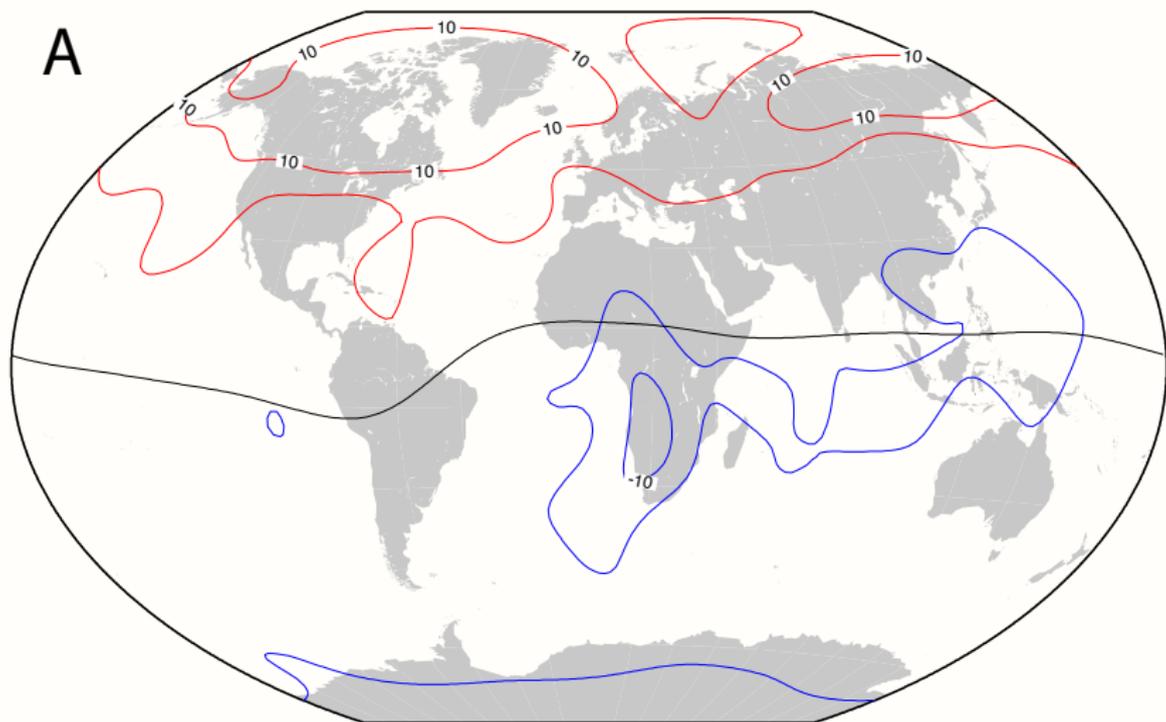


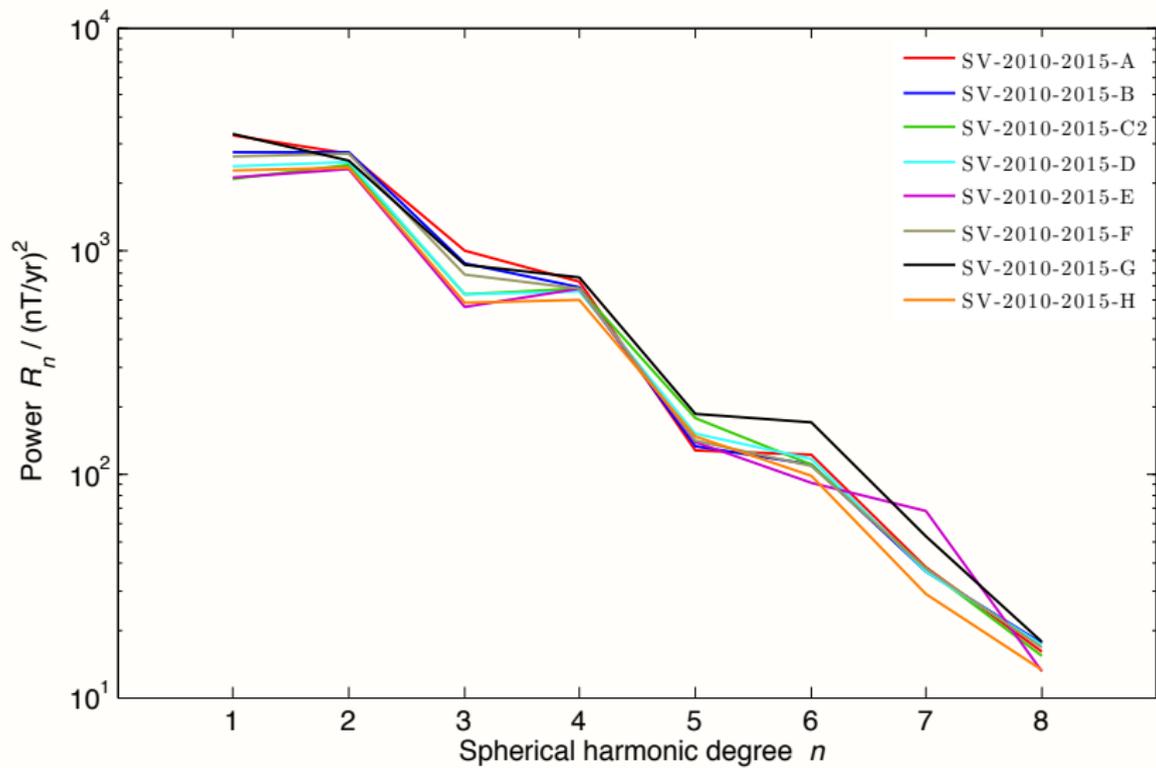


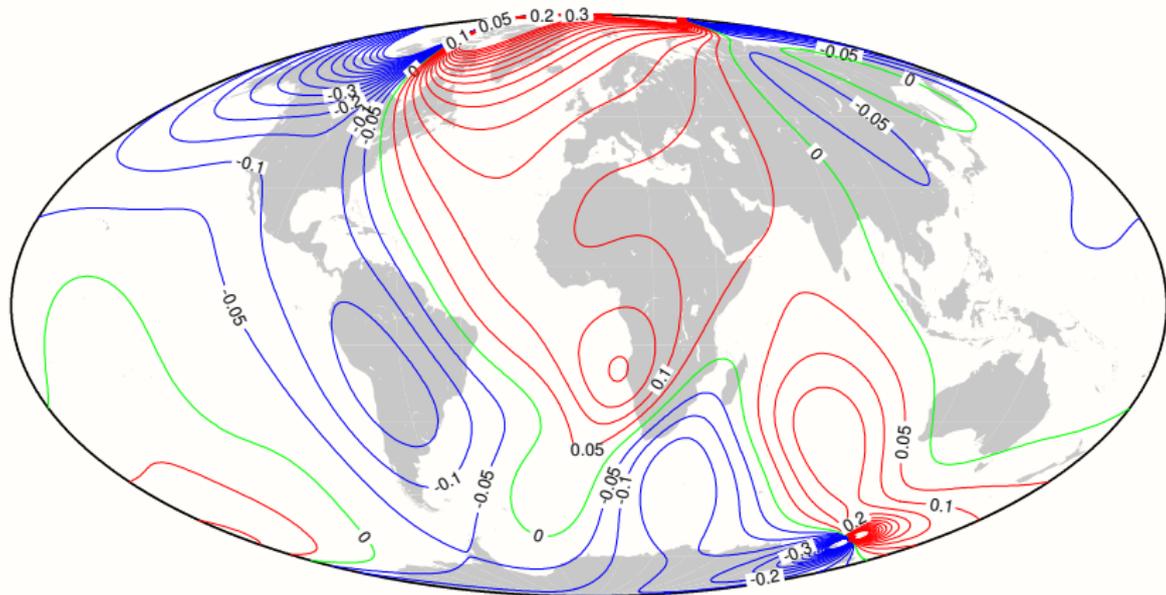












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